Extreme-Precision MEMS Segmented Deformable Mirror (NASA Phase II SBIR)

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NASA Mirror Technology Days

July 31st – August 2nd, 2007



Iris AO Introduction

- Founded in 2002
- Based in Berkeley, CA
- Small high-technology firm specializing in MEMS AO
 - High-performance, robust MEMS based DMs that address a large application space
 - Multi-channel high-voltage drive electronics
 - AO imaging systems



Segmented MEMS DM Schematic



- Robust assembled mirror surface stays flat (0.56 nm/°C PV)
- Temperatureinsensitive bimorphs elevate mirror above substrate (14 nm/°C, σ=0.8 nm/°C)
- Piston/tip/tilt electrostatic actuation



37-Segment PTT DM Images





3.5 mm inscribed aperture

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Step Response



120/140 μs rise/fall times, 20-80%; 1.63 μm, 36 V DMs can survive ~350 G shock/vibration unpowered

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Phase II SBIR Goals

Performance Period: Jan 29 2007 – Jan 28, 2009

Specification	Current DMs	Phase II Demo Goal*	Phase II Study Goal
Surface Figure Errors (nm rms)	6-20	1-3	0.1
Positioning resolution (nm rms)	5 (elect noise limited)	0.14	0.04
Open-loop positioning accuracy (rms)	20-30 nm	10 nm	Not Specified
Stability (nm <i>rms)</i> • over 15-60 min	0.2-1.2 (5 elect. noise)	0.2	0.04
Failure Testing: Continue testing and determine techniques to eliminate			

Failure Testing: Continue testing and determine techniques to eliminate potential snap-in failures

* Independent verification by the Lab for AO at UC Santa Cruz



Surface Figure Error

- Current designs: 6-20 nm rms
 - Single-crystal silicon segments
 - Segment thickness = 20 µm
- Thicker ⇒ Flatter
 - Surface figure errors ∝1/t²⁻³
 - DMs with 25 and 30 µm nearly complete
 - 1.6-2X/2.3-3.4X improvement
 - 50 µm mirror wafers damaged in processing







Extreme-Positioning Resolution

Smart Driver Electronics

- 50 mV rms SH refresh noise
- 3.2khz (SH DAC update rate)
- ~ 5 nm *rms* position noise (current DM design)
- Quantization noise: 2.5 mV (14.5 bits, 200V)



Smart Driver II Elect. Breadboard

- 3.3 mV rms electrical noise
- High frequency
- 0.3 nm *rms* position noise (current DM design)
- Quantization noise: 3.5 mV (14 bits, 200V)





Smart Driver II Specifications

- 14 bit
- 200 V
- Compact version: 128 channels
- 2U 19" rack mount: 512 channels/box
- (Low speed) USB scales to 64k channels (128 x 512 channels)
- High speed interface will scale to >4k channels/interface
 - Preliminary planning stage

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Extreme-Positioning Resolution Limits

- Current S37-5 DM uses only 1/3rd of the Smart Driver dynamic range
- Redesign DM to use all dynamic range
- Use more linear region

⇒ 0.14 nm rms resolution with 14 bits, 2.5 µm stroke





August 1st,

Open Loop Positioning Accuracy

11

- Open loop controller linearizes response
- Prevents snap-in failures by limiting controls to safe operating region - "reachable space"



Iris AO, Inc. Open-Loop Positioning Accuracy







nm-Level Positioning Stability



- Stability to 0.21-1.17 nm rms over 15 best minutes (75-90)
- Interferometry does not pick up electronics noise
- Temperature stable to 0.2°C
- Independent testing to be done by the CfAO/LAO

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Scalability

- **Currently selling 37-segment** DMs
- Scalable drive electronics
 - NASA Phase II SBIR
- 127-segment DM
 - **Funding from NIH Phase** II SBIR under administrative review
- 400-1200 segment DM
 - Funding TBD
 - Preliminary experiments where possible
 - Bonding experiments underway





Summary

- Presently shipping 5 µm stroke, 37-segment DMs
 - 20 nm rms surface figures errors
 - 14.5 bit control, 5 nm rms noise floor
 - Precision open-loop positioning
 - Stable DM
- Phase II Progress
 - Low-noise Electronics mostly assembled
 - Testing begins September
 - DMs with flatter segments nearly complete
 - Testing begins September
 - Expect DMs with 3-12/2-8 nm rms



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CIAD

 National Eye Institute – Phase I SBIR (DM Process Development)

BSAC

- I R43 EY015381-01
- US Air Force Phase II SBIR (DM Control)

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