



Tools for visualizing the solution space for freeform three-mirror anastigmats

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Outline

- 1. Introduction to TMA design
- 2. General solution for single-conic axial TMA
- 3. Creating a useful program for visualizing TMA space
- 4. Surveying TMA solution space
- 5. Conclusion









What is a conventional TMA?

TMA = Three Mirror Anastigmat

A co-axial three mirror system corrected for the primary 3rd order (4th order in wavefront) aberrations (spherical, coma, and astigmatism).

 $W_{040} = 0, W_{131} = 0, W_{222} = 0$

- A system with 2 spherical mirrors and 1 conic mirror can achieve this correction.
- As Rakich shows [1, 2], a subset of these systems also has a flat field (no Petzval curvature)
- Many of these solutions have significant obscurations
 - To reduce obscurations, use field and aperture bias to select off-axis sections of co-axial mirrors
- Such surfaces may become sensitive to tilts and decenters











What is a freeform "TMA"?

- A freeform TMA typically begins from an obscured coaxial TMA design, and then the surfaces are tilted to avoid obscurations
 - Tilting surfaces introduces, primarily, large amounts of astigmatism and coma
- To correct the aberrations induced by tilting the surfaces, we need more degrees of freedom
 - Zernike surfaces
 - NURBS
 - 2D Chebyshev polynomials
 - 2D Forbes polynomials
 - Radial basis functions
- The resulting system is no longer a proper "TMA" type design, as the 4th order wavefront aberration coefficients are no longer zero, but instead are used to balance higher order terms ("reflective triplet" is more accurate)





Un-obscured FF-TMA







TMA solution space maps

The Three Mirror Anastigmat design space for 2 spheres and 1 conic has been mapped out by Rakich [1, 2]

- Solution is based on the "plate diagram" by Burch [3]
- 2 spherical and 1 conic mirror creates a total of 4 "plates"
- Solve for system parameters by substituting them into the plate equations, which are then solved
- By fixing the radius of the primary, and given t_1 (primary-tosecondary distance) and c_2 (secondary curvature), the equations to correct spherical, coma, and astigmatism result in a cubic equation for c_3 (tertiary curvature)
- The solution space is then mapped out on a t_1 - c_2 plane (figure to the right)
- Due to the cubic equation, there are 3 solutions for each of 4 geometries, for a total of 12 solution maps.

Burch Plate Equations $W_1 + W_2 + W_3 + W_4 = 0$ $W_1 x_1 + W_2 x_2 + W_3 x_3 + W_4 x_4 = 0$ $W_1 x_1^2 + W_2 x_2^2 + W_3 x_3^2 + W_4 x_4^2 = 0$









TMA solutions – conic on primary (AS1)











TMA solutions - Conic on secondary (AS2)











Purpose of this study

Purpose:

To enable the design of large aperture, wide field-of-view, unobscured telescope designs:

- 4° circular full FOV
- 300 mm aperture
- Broad spectral coverage (UV, Vis., NIR, FIR)
- Compact footprint

Method:

Survey solutions to select candidate starting points for further freeform study, including solutions with negative primaries not considered in Rakich's study









Creating a useful GUI for visualizing **Rakich TMA solutions**

- Programmed in MATLAB
- 3 solution maps to cubic Rakich equations are plotted on top
- Select which solution(s) to plot/update
 - Select which surface is aspherized
 - Select the sign of the primary mirror
 - Select which cubic solution (A, B, C)
- Interactively change the plot regions and plot resolution by typing the range directly or selecting the region of interest with the mouse
- Select a point on the plots to display the layout (using CODE V ® via COM interface)
- Display the Y-Ybar plot of the selected point, with bounding box lines









AS1SC-N – flat field region











AS1SC-N – Region 2 – Flat Field





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AS1SC-N – Region 2 – Flat Field





















Survey results

- This survey showed that most of these solutions are outside of the range of feasibility (as Rakich also found)
 - Extreme distances between mirrors
 - High curvatures
 - Large apertures
- We can apply filters to show the regions which have reasonable solutions
- Rakich did not consider solutions with negative primary mirrors because of their obscurations, but as we know from Pathfinder 1 [4], freeform solutions with negative primaries are possible.
 - There are multiple candidate solutions for further freeform study with negative primaries









AS1 Filtered



AS1SB Solution, positive primary





Positive Primary



Negative Primary





t.(m)











AS2 Filtered







0.5 1 1.5 2 2.5 3 t₁(m) AS2SC Solution, negative primary

Positive Primary



Negative Primary



AS2SA Solution, negative primary



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0.5

1

1.5

2.5

3

2







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Interesting solutions from this study









Interesting solutions from filters

AS1SA-P

AS2SC-P











Conclusion

- Using Rakich's equations for 2 spheres, 1 conic type TMAs, we have created a program and GUI to survey these solutions (extending to negative primaries)
- Using this tool, we have surveyed the design space for co-axial TMAs while applying filters applicable for transforming those solutions into freeform TMAs
- From these results, we selected interesting forms for further freeform study, including both positive and negative primary solutions
- Comparison of results from the freeform study is in progress









References

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